# EXPECTATION FORMULAS 

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November 2010

In the formulas given below, $U, W, X, Y$ are any unknowns, and $A, B, C, D, K$, are any statements, unless otherwise specified. $E(X \mid A)$ is the Expected Value of $X$ given $A$. Always $I_{A}$ denotes the Indicator unknown for the statement $A$, and this means $I_{A}$ is one or zero according to whether $A$ is true or false. Definite real numbers are denoted by lower case symbols $a, b, c, d, u, v, w, x, y, z$ and are also referred to as constants. Unknowns can be added and multiplied and all constants are also considered as unknowns. Think of any description of a numerical quantity as being an unknown, so since 3 or $\pi$ describe numerical quantities they are unknowns. The unknowns form a set $\mathcal{A}$ containing the set of all real numbers $\mathbb{R}$. We call $\mathcal{A}$ the Algebra of Unknowns.

## 1. FUNDAMENTAL AXIOMS

## INFORMATION CANNOT BE IGNORED

$$
E(X \mid(X=a) \& B)=a
$$

CONSEQUENCE (since $a=a$ )

$$
E(a \mid B)=a
$$

## ORDER AXIOM

$$
[B \Rightarrow(X \leq Y)] \Rightarrow E(X \mid B) \leq E(Y \mid B)
$$

## 2. ADDITION AXIOM

$$
E(a \cdot X \pm b \cdot Y \mid B)=a \cdot E(X \mid B) \pm b \cdot E(Y \mid B)
$$

3. MULTIPLICATION RULE (follows from the assumption that $E\left(X \cdot I_{A} \mid B\right)$ as a function of $X$ depends only on the number $E(X \mid A \& B)$ for any fixed $A, B$, by then taking $X=a$ and evaluating both $E\left(X \cdot I_{B} \mid C\right)$ and $\left.E(X \mid B \& C)\right)$

$$
E\left(X \cdot I_{B} \mid C\right)=E(X \mid B \& C) \cdot E\left(I_{B} \mid C\right)
$$

## 4. DEFINITION OF PROBABILITY

$$
P(A \mid B)=E\left(I_{A} \mid B\right)
$$

5. NOTATION (when the given $A$ is understood or is the same throughout)

$$
\mu_{X}=E(X)=E(X \mid A), E(X \mid B)=E(X \mid B \& A), P(B \mid A)=P(B)
$$

## MULTIPLICATION RULE AND PROBABILITY

$$
E\left(X \cdot I_{B}\right)=\underset{1}{E(X \mid B) \cdot P(B)}
$$

## 6. LOGIC CONVERTED TO ALGEBRA

$$
\begin{gathered}
I_{A \& B}=I_{A} \cdot I_{B} \\
I_{A \text { or } B}=I_{A}+I_{B}-I_{A \& B} \\
I_{n o t} A=1-I_{A}
\end{gathered}
$$

7. MULTIPLICATION RULE FOR PROBABILITY (use $X=I_{A}$ in Multiplication Rule and definition of probability)

$$
P(A \& B)=P(A \mid B) \cdot P(B)
$$

8. RULES OF PROBABILITY (follow from $0 \leq I_{A} \leq 1$, the conversion of logic to algebra, the axioms, and the definition of probability)

$$
\begin{gathered}
0 \leq P(A) \leq 1 \\
P(A \text { or } B)=P(A)+P(B)-P(A \& B) \\
P(\text { not } A)=1-P(A)
\end{gathered}
$$

9. PARTITION PRINCIPLE (consequence of axioms and Multiplication Rule)

If $B_{1}, B_{2}, B_{3}, \ldots, B_{n}$ are statements and exactly one is true (called a Partition), then

$$
\begin{gathered}
\sum_{k=1}^{n} I_{B_{k}}=1, \sum_{k=1}^{n} P\left(B_{k}\right)=1 \\
X=\sum_{k=1}^{n} X \cdot I_{B_{k}} \\
E(X)=\sum_{k=1}^{n} E\left(X \mid B_{k}\right) \cdot P\left(B_{k}\right) \\
P(A)=\sum_{k=1}^{n} P\left(A \mid B_{k}\right) \cdot P\left(B_{k}\right)
\end{gathered}
$$

## 10. BAYES' RULES

$$
\begin{gathered}
P(A \mid B) \cdot P(B)=P(A \& B)=P(B \& A)=P(B \mid A) \cdot P(A) \\
P(A \mid B)=\frac{P(A \& B)}{P(B)}=\frac{P(B \mid A) \cdot P(A)}{P(B)} \\
\frac{P(A \mid B)}{P(A)}=\frac{P(B \mid A)}{P(B)}
\end{gathered}
$$

## 11. DEFINITION OF COVARIANCE

$$
\operatorname{Cov}(X, Y)=E\left(\left[X-\mu_{X}\right] \cdot\left[Y-\mu_{Y}\right]\right)
$$

12. DEFINITION OF VARIANCE

$$
\operatorname{Var}(X)=\operatorname{Cov}(X, X)
$$

13. DEFINITION OF STANDARD DEVIATION

$$
S D(X)=\sigma_{X}=\sqrt{\operatorname{Var}(X)}
$$

14. DEFINITION OF CORRELLATION

$$
\rho=\rho(X, Y)=\frac{\operatorname{Cov}(X, Y)}{\sigma_{X} \cdot \sigma_{Y}}
$$

15. DEFINITION OF STANDARDIZATION

$$
Z_{X}=\frac{X-\mu_{X}}{\sigma_{X}}, \quad X=\mu_{X}+\sigma_{X} \cdot Z_{X}
$$

16. CALCULATION FORMULAS

$$
\begin{gathered}
\operatorname{Cov}(X, Y)=E(X \cdot Y)-\mu_{X} \cdot \mu_{Y}=\rho \cdot \sigma_{X} \cdot \sigma_{Y} \\
E(X \cdot Y)=\mu_{X} \cdot \mu_{Y}+\operatorname{Cov}(X, Y) \\
\operatorname{Var}(X \pm Y)=\operatorname{Var}(X)+\operatorname{Var}(Y) \pm 2 \operatorname{Cov}(X, Y) \\
\rho=\operatorname{Cov}\left(Z_{X}, Z_{Y}\right)=E\left(Z_{X} \cdot Z_{Y}\right) \\
\operatorname{Cov}(X, c)=0, \operatorname{Cov}(X, Y)=\operatorname{Cov}(Y, X), \operatorname{Var}(X \pm c)=\operatorname{Var}(X)
\end{gathered}
$$

$\operatorname{Cov}(W, a \cdot X \pm b \cdot Y)=a \cdot \operatorname{Cov}(W, X) \pm b \cdot \operatorname{Cov}(W, Y), \operatorname{Var}(c \cdot X)=c^{2} \cdot \operatorname{Var}(X)$
17. LINEAR REGRESSION (of $Y$ on $X$, with $W=\beta_{0}+\beta_{1} \cdot X$ and $R_{Y}=W_{X}-Y$ )

$$
\begin{gathered}
E(Y \mid X=x)=\beta_{0}+\beta_{1} \cdot x \\
\beta_{1}=\rho \cdot \frac{\sigma_{Y}}{\sigma_{X}}, \beta_{0}=\mu_{Y}-\beta_{1} \cdot \mu_{X} \\
E\left(R_{Y}^{2}\right)=\sigma_{Y}^{2} \cdot\left(1-\rho^{2}\right)
\end{gathered}
$$

For $W=a+b X$, and $R=W-Y$,

$$
\begin{gathered}
E\left(R^{2}\right)=[E(R)]^{2}+\operatorname{Var}(R)=\left[\left(a+b \mu_{X}\right)-\mu_{Y}\right]^{2}+\operatorname{Var}(W)+\operatorname{Var}(Y)-2 \operatorname{Cov}(W, Y) \\
=\left[\left(a+b \mu_{X}\right)-\mu_{Y}\right]^{2}+b^{2} \sigma_{X}^{2}+\sigma_{Y}^{2}-2 b \rho \sigma_{X} \sigma_{Y} \\
=\left[\left(a+b \mu_{X}\right)-\mu_{Y}\right]^{2}+\left(1-\rho^{2}\right) \sigma_{Y}^{2}+\left(\rho \sigma_{Y}\right)^{2}+\left(b \sigma_{X}\right)^{2}-2\left(\rho \sigma_{Y}\right)\left(b \sigma_{X}\right) \\
=\left[\left(a+b \mu_{X}\right)-\mu_{Y}\right]^{2}+\left(1-\rho^{2}\right) \sigma_{Y}^{2}+\left[\left(\rho \sigma_{Y}\right)-\left(b \sigma_{X}\right)\right]^{2}
\end{gathered}
$$

18. CUMULATIVE DISTRIBUTION FUNCTION

$$
\begin{gathered}
F_{X}(x)=P(X \leq x), x \in \mathbb{R} \\
P(a<X \leq b)=F_{X}(b)-F_{X}(a)
\end{gathered}
$$

19. PROBABILITY DISTRIBUTION FUNCTION (for discrete unknown)

$$
p_{X}(k)=P(X=k), k \in \mathbb{R}
$$

20. PROBABILITY DENSITY FUNCTION

$$
\begin{gathered}
f_{X}(x)=F_{X}^{\prime}(x)=\left(\frac{d}{d x} F_{X}\right)(x), x \in \mathbb{R} \\
P(a<X \leq b)=F_{X}(b)-F_{X}(a)=\int_{a}^{b} f_{X}(x) d x
\end{gathered}
$$

21. TRANSFORM

$$
\begin{gathered}
{[\mathcal{M}(h)](t)=\int_{-\infty}^{\infty} e^{t x} h(x) d x=\int_{-\infty}^{\infty} \exp (t x) \cdot h(x) d x} \\
e^{x}=\sum_{n=0}^{\infty} \frac{x^{n}}{n!} \\
\mathcal{M}(a \cdot g \pm b \cdot h)=a \cdot \mathcal{M}(g) \pm b \cdot \mathcal{M}(h) \\
{[\mathcal{M}(x \cdot h)](t)=\left[\frac{d}{d t} \mathcal{M}(h)\right](t)}
\end{gathered}
$$

For $A(x)$ the statement that $x$ is in the interval $[a, b] \subset \mathbb{R}$, we denote $I_{A(x)}$ by $I_{[a, b]}(x)$

$$
\begin{gathered}
\int_{-\infty}^{\infty} I_{[a, b]}(x) \cdot h(x) d x=\int_{a}^{b} h(x) d x \\
{\left[\mathcal{M}\left(I_{[a, b]}\right)\right](t)=\frac{e^{b t}-e^{a t}}{t}=\sum_{n=0}^{\infty}\left[b^{n+1}-a^{n+1}\right] \frac{t^{n}}{(n+1)!}=\sum_{n=0}^{\infty} \frac{\left[b^{n+1}-a^{n+1}\right]}{n+1} \frac{t^{n}}{n!}} \\
f(t)=\sum_{n=0}^{\infty} \frac{f^{(n)}(c)}{n!}(t-c)^{n}=\sum_{n=0}^{\infty} f^{(n)}(c) \frac{(t-c)^{n}}{n!}, f^{(n)}=\frac{d^{n}}{d x^{n}} f
\end{gathered}
$$

## 22. MOMENT GENERATING FUNCTION

$$
\begin{gathered}
m_{X}=E\left(e^{t X}\right)=\mathcal{M}\left(f_{X}\right) \\
m_{X}^{(n)}(t)=E\left(X^{n} e^{t X}\right), n=0,1,2,3, \ldots \\
m_{X}^{(n)}(0)=E\left(X^{n}\right), n=0,1,2,3, \ldots \\
m_{X \pm c}(t)=e^{ \pm c t} \cdot m_{X}(t) \\
m_{c X}(t)=m_{X}(c t)
\end{gathered}
$$

## 23. DIRAC DELTA FUNCTION

Not really a function but it is denoted $\delta$ with the property that for any smooth function $h$ with compact support

$$
\begin{gathered}
h(0)=\int_{-\infty}^{\infty} h(x) \delta(x) d x \\
\delta_{c}(x)=\delta(x-c) \\
h(c)=\int_{-\infty}^{\infty} h(x) \delta_{c}(x) d x \\
\mathcal{M}\left(\delta_{c}\right)(t)=e^{c t}
\end{gathered}
$$

If $A_{1}, A_{2}, A_{3}, \ldots, A_{n}$ is a partition, $v_{1}, v_{2}, v_{3}, \ldots, v_{n} \in \mathbb{R}$, then

$$
X=\sum_{k=1}^{n} v_{k} \cdot I_{A_{k}}
$$

is a Simple Unknown and

$$
\begin{gathered}
m_{X}(t)=\sum_{k=1}^{n} P\left(A_{k}\right) \cdot e^{v_{k} t}=\mathcal{M}\left(f_{X}\right) \\
f_{X}(x)=\sum_{k=1}^{n} P\left(A_{k}\right) \cdot \delta_{v_{k}}
\end{gathered}
$$

## 24. UNIFORM DISTRIBUTION

If $X$ is uniformly distributed on $[a, b]$ then

$$
\begin{gathered}
f_{X}=\frac{1}{b-a} \cdot I_{[a, b]} \\
m_{X}(t)=\frac{1}{b-a} \mathcal{M}\left(I_{[a, b]}\right)=\frac{e^{b t}-e^{a t}}{(b-a) t}=\sum_{n=0}^{\infty}\left[\frac{b^{n+1}-a^{n+1}}{(n+1)(b-a)}\right] \frac{t^{n}}{n!} \\
E\left(X^{n}\right)=\frac{b^{n+1}-a^{n+1}}{(n+1)(b-a)} \\
E(X)=\frac{a+b}{2} \\
\sigma_{X}=\frac{(b-a) / 2}{\sqrt{3}}
\end{gathered}
$$

## 25. NORMAL DISTRIBUTION

$$
\begin{gathered}
\mu=E(X), \sigma=S D(X) \\
f_{X}(x)=\frac{1}{\sigma \sqrt{2 \pi}} \exp \left(-\frac{1}{2}\left[\frac{x-\mu}{\sigma}\right]^{2}\right)
\end{gathered}
$$

For $Z$ standard normal $(\mu=0, \sigma=1)$

$$
\begin{gathered}
f_{Z}(z)=\frac{1}{\sqrt{2 \pi}} \exp \left(-\frac{1}{2} z^{2}\right) \\
m_{Z}(t)=e^{t^{2} / 2}=\sum_{n=0}^{\infty} \frac{(2 n)!}{2^{n} \cdot n!} \frac{t^{2 n}}{(2 n)!}, E\left(Z^{n}\right)=\frac{(2 n)!}{2^{n} \cdot n!}=(2 n-1)!!
\end{gathered}
$$

26. SAMPLING DISTRIBUTIONS

Start with any random variable $X$ and let $X_{1}, X_{2}, X_{3}, \ldots, X_{n}$ be observations of $X$.

$$
\begin{gathered}
E\left(X_{k}\right)=\mu_{X}, S D\left(X_{k}\right)=\sigma_{X}, k=1,2,3, \ldots, n \\
\bar{X}_{n}=\frac{1}{n} T_{n}, T_{n}=\sum_{k=1}^{n} X_{k} \\
\overline{X-\bar{X}_{n}}=\sum_{k=1}^{n}\left(X_{k}-\bar{X}_{n}\right)=0, \overline{\left(X-\bar{X}_{n}\right)^{2}}=\frac{1}{n} \sum_{k=1}^{n}\left(X_{k}-\bar{X}\right)^{2} \\
E\left(T_{n}\right)=n \mu_{X}, E\left(\bar{X}_{n}\right)=\mu_{X} \\
\overline{(X-\bar{X})^{2}}=\overline{X^{2}}-[\bar{X}]^{2}
\end{gathered}
$$

## FAIR SAMPLING CONSTANT/CONDITION

$$
c=\frac{\operatorname{Cov}\left(X_{k}, T_{n}\right)}{\sigma_{X}^{2}}, k=1,2,3, \ldots, n
$$

Then

$$
\begin{gathered}
\operatorname{Var}\left(T_{n}\right)=c \cdot n \sigma_{X}^{2}, S D\left(T_{n}\right)=\sqrt{c} \cdot \sqrt{n} \cdot \sigma_{X}, S D\left(\bar{X}_{n}\right)=\sqrt{c} \frac{\sigma_{X}}{\sqrt{n}}, \operatorname{Var}\left(\bar{X}_{n}\right)=c \frac{\sigma_{X}^{2}}{n} \\
S^{2}=\frac{n}{n-c} \overline{(X-\bar{X})^{2}}, E\left(S^{2}\right)=\sigma_{X}^{2}
\end{gathered}
$$

Denote Independent Random Sampling by $I R S$ and Simple Random Sampling by $S R S$. Here $N$ is population size, $n$ is sample size.

$$
\begin{gathered}
c_{I R S}=1, c_{S R S}=\frac{N-n}{N-1} \\
S D\left(\bar{X}_{n}\right)_{I R S}=\frac{\sigma_{X}}{\sqrt{n}}, S D\left(T_{n}\right)_{I R S}=\sqrt{n} \sigma_{X} \\
S D\left(\bar{X}_{n}\right)_{S R S}=\sqrt{c_{S R S}} \cdot S D\left(\bar{X}_{n}\right)_{I R S}=\sqrt{\frac{N-n}{N-1}} \cdot \frac{\sigma_{X}}{\sqrt{n}} \\
S D\left(T_{n}\right)_{S R S}=\sqrt{c_{S R S}} \cdot S D\left(T_{n}\right)_{I R S}=\sqrt{\frac{N-n}{N-1}} \cdot \sqrt{n} \sigma_{X} \\
\frac{n}{n-c_{I R S}}=\frac{n}{n-1} \\
\frac{n}{n-c_{S R S}}=\frac{N-1}{N} \cdot \frac{n}{n-1}=\frac{N-1}{N} \cdot \frac{n}{n-c_{I R S}} \\
\left(S^{2}\right)_{S R S}=\frac{N-1}{N}\left(S^{2}\right)_{I R S}
\end{gathered}
$$

## 27. CHI-SQUARE DISTRIBUTION

Begin with standard normal $Z$ and let $Z_{1}, Z_{2}, Z_{3}, \ldots, Z_{d}$ be an independent random sample of size $d$. Define $W_{d}$ and $\chi_{d}^{2}$ by

$$
\chi_{d}^{2}=f_{W^{2}}, W_{d}^{2}=\sum_{k=1}^{d} Z_{k}^{2}, m_{W^{2}}(t)=(1-2 t)^{-d / 2}
$$

If $X$ is normal and IRS is used, then

$$
f_{U}=\chi_{n-1}^{2}, \text { where } U=\frac{(n-1) S^{2}}{\sigma_{X}^{2}}, \text { and } S^{2}=\frac{n}{n-1} \overline{\left(X-\bar{X}_{n}\right)^{2}}
$$

The random variable $W_{d}^{2}$ is said to have the Chi-Square Distribution with $d$-Degrees of Freedom.

## 28. TWO RANDOM VARIABLE SAMPLING

Start with two random variables $X$ and $Y$ on the same population with paired observations $\left.\left(X_{1}, Y_{1}\right),\left(X_{2}, Y_{2}\right), X_{3}, Y_{3}\right), \ldots,\left(X_{n}, Y_{n}\right)$.

$$
\begin{gathered}
\operatorname{Cov}(X, Y)=\rho \cdot \sigma_{X} \cdot \sigma_{Y} \\
F_{X_{k}}=F_{X}, E\left(X_{k}\right)=\mu_{X}, S D\left(X_{k}\right)=\sigma_{X}, k=1,2,3, \ldots, n \\
F_{Y_{k}}=F_{Y}, E\left(Y_{k}\right)=\mu_{Y}, S D\left(Y_{k}\right)=\sigma_{Y}, k=1,2,3, \ldots, n \\
T_{X}=\sum_{k=1}^{n} X_{k}, T_{Y}=\sum_{k=1}^{n} Y_{k} \\
\operatorname{Cov}\left(X_{k}, Y_{k}\right)=\rho \cdot \sigma_{X} \cdot \sigma_{Y}, k=1,2,3, \ldots, n \\
\overline{\left(X-\bar{X}_{n}\right)\left(Y_{k}-\bar{Y}_{n}\right)}=\frac{1}{n} \sum_{k=1}^{n}\left(X_{k}-\bar{X}_{n}\right)\left(Y_{k}-\bar{Y}_{n}\right) \\
\frac{(X-\bar{X})(Y-\bar{Y})}{(X Y}-[\bar{X}][\bar{Y}]
\end{gathered}
$$

FAIR PAIRING CONDITIONS/CONSTANTS

$$
\begin{gathered}
c_{X}=\frac{\operatorname{Cov}\left(X_{k}, T_{X}\right)}{\sigma_{X}^{2}}, c_{Y}=\frac{\operatorname{Cov}\left(Y_{k}, T_{Y}\right)}{\sigma_{Y}^{2}}, k=1,2,3, \ldots, n \\
d=\frac{\operatorname{Cov}\left(X_{k}, T_{Y}\right)}{\left(\sqrt{c_{X}} \sigma_{X}\right) \cdot\left(\sqrt{c_{Y}} \sigma_{Y}\right)}, k=1,2,3, \ldots, n \\
e=\frac{\operatorname{Cov}\left(T_{X}, Y_{k}\right)}{\left(\sqrt{c_{X}} \sigma_{X}\right) \cdot\left(\sqrt{c_{Y}} \sigma_{Y}\right)}, k=1,2,3, \ldots, n
\end{gathered}
$$

Define

$$
c=\sqrt{c_{X} \cdot c_{Y}}
$$

It follows that $d=e$ and in fact $\rho\left(T_{X}, T_{Y}\right)=d=e=\rho\left(\bar{X}_{n}, \bar{Y}_{n}\right)$

$$
\begin{aligned}
& \operatorname{Cov}\left(T_{X}, T_{Y}\right)=n c d \sigma_{X} \sigma_{Y}=\rho\left(T_{X}, T_{Y}\right)\left(\sqrt{c_{X} n} \sigma_{X}\right)\left(\sqrt{c_{Y} n} \sigma_{Y}\right) \\
& \operatorname{Cov}\left(\bar{X}_{n}, \bar{Y}_{n}\right)=\frac{1}{n} c \cdot d \cdot \sigma_{X} \cdot \sigma_{Y}=d \cdot\left(\sqrt{c_{X}} \frac{\sigma_{X}}{\sqrt{n}}\right) \cdot\left(\sqrt{c_{Y}} \frac{\sigma_{Y}}{\sqrt{n}}\right)
\end{aligned}
$$

For SRS it is reasonable that $\operatorname{Cov}\left(X_{k}, Y_{l}\right)$ for $k \neq l$ is otherwise independent of $k, l$ and this implies

$$
d_{I R S}=\rho=d_{S R S}
$$

Moreover, for SRS,

$$
c_{X}=\frac{N-n}{N-1}=c_{Y}=c_{S R S}
$$

On the other hand, if $\rho=0$, then it is reasonable that $\operatorname{Cov}\left(X_{k}, Y_{l}\right)=0$ for any $k, l$, and thus in general, we can write

$$
d=a \rho
$$

Then

$$
E(\overline{(X-\bar{X})(Y-\bar{Y})})=\left(1-\frac{a c}{n}\right) \operatorname{Cov}(X, Y)
$$

so in general,

$$
\left.E\left(\left[\frac{n}{n-a c}\right] \overline{(X-\bar{X})(Y-\bar{Y})}\right)\right)=\operatorname{Cov}(X, Y)
$$

and

$$
a_{I R S}=1=a_{S R S}
$$

so

$$
\left.E\left(\left[\frac{n}{n-c}\right] \overline{(X-\bar{X})(Y-\bar{Y})}\right)\right)=\operatorname{Cov}(X, Y), \text { for } I R S \text { or } S R S
$$

## 29. The t-DISTRIBUTION

Suppose that $Z_{0}$ and $W_{d}^{2}$ are independent random variables, that $Z_{0}$ is standard normal and that $W_{d}^{2}$ has chi-square distribution for $d$ degrees of freedom. Then

$$
t_{d}=\frac{Z_{0}}{\sqrt{\frac{W_{d}^{2}}{d}}}
$$

has what is called the Student $t$-Distribution for $d$ Degrees of Freedom.
If $Z_{0}, Z_{1}, Z_{2}, \ldots, Z_{d}$ are all mutually independent standard normal random variables, then with

$$
W_{d}^{2}=\sum_{k=1}^{d} Z_{k}^{2}
$$

the random variable the random variable $W_{d}^{2}$ has the chi-square distribution for $d$ degrees of freedom and is indepedent of $Z_{0}$, so $t_{d}$ can be defined as

$$
t_{d}=\frac{Z_{0}}{\sqrt{\frac{W_{d}^{2}}{d}}}
$$

with this specific choice of $W_{d}^{2}$.
As $d \rightarrow \infty$ the distribution of $t_{d}$ becomes standard normal.

## 30. SAMPLING TO ESTIMATE THE MEAN

If $X$ is a random variable with known standard deviation $\sigma_{X}$ but with unknown mean, not a common circumstance, then in case $\bar{X}_{n}$ is normal, a confidence interval for the mean can easily be given for any Level of Confidence usually denoted $C$. The confidence level is usually specified in advance and we seek a Margin of Error denoted $M$ so that

$$
P\left(\left|\bar{X}_{n}-\mu_{X}\right| \leq M\right)=C
$$

We can standardize $\bar{X}_{n}$ and denote the result simply by $Z$, so $Z$ is standard normal and using the inverse normal we choose $z_{C}$ so that

$$
P\left(|Z| \leq z_{C}\right)=C
$$

Then

$$
M=z_{C} \cdot S D\left(\bar{X}_{n}\right)
$$

Suppose $X$ is a random variable and the sample unknowns $X_{1}, X_{2}, X_{3}, \ldots, X_{n}$ forming a sample of size $n$ for $X$ are pairwise uncorrelated, which is true in case of IRS. Then the random variables $X_{2}-\bar{X}_{1}, X_{3}-\bar{X}_{2}, \ldots, X_{n}-\bar{X}_{n-1}, \bar{X}_{n}$ are all pairwise uncorrelated. Let $Z_{k}$ denoting the standardization of $X_{k+1}-\bar{X}_{k}$, for $k<n$, and let $Z_{0}$ be the standardization of $\bar{X}_{n}$. We then have

$$
\frac{(n-1) S^{2}}{\sigma_{X}^{2}}=\sum_{k=1}^{n-1} Z_{k}^{2}=W_{n-1}^{2}
$$

and

$$
\frac{\bar{X}_{n}-\mu_{X}}{S / \sqrt{n}}=\frac{\bar{X}_{n}-\mu_{X}}{\sigma_{X} / \sqrt{n}} \cdot \frac{1}{\sqrt{\frac{(n-1) S^{2}}{(n-1) \sigma_{X}^{2}}}}=\frac{Z_{0}}{\sqrt{\frac{W_{n-1}^{2}}{n-1}}}=t_{n-1}
$$

If $X$ is normal and we have IRS, then as $Z_{0}, Z_{1}, Z_{2}, \ldots, Z_{n-1}$ are all pairwise uncorrelated and formed as linear combinations of the independent normal random variables $X_{1}, X_{2}, X_{3}, \ldots, X_{n}$, it follows from linear algebra that in fact $Z_{0}, Z_{1}, \ldots, Z_{n-1}$ are all independent standard normal random variables, and therfore $t_{n-1}$ has the $t$-distribution for $n-1$ degrees of freedom. We can therefore use the inverse t-distribution in place of the inverse standard normal when we need to use $s$ in place of $\sigma_{X}$, so denoting $t_{C}$ the number chosen so that

$$
P\left(\left|t_{n-1}\right| \leq t_{C}\right)=C
$$

we have now

$$
M=t_{C} \cdot s
$$

with $s$ the value of the sample standard deviation from the sample data.

## 31. SAMPLING TO ESTIMATE VARIANCE

If $X$ is a normal random variable and we need to estimate both $\mu_{X}$ and $\sigma_{X}$, then the problem of estimating $\sigma_{X}$ actually comes first, since it is used in estimating $\mu_{X}$. As noted in (27. ChiSquare Distribution), the distribution of $(n-1) S^{2} / \sigma_{X}^{2}$ is chi-square with $n-1$ degrees of freedom. Thus, to make a confidence interval with confidence level $C$, we use $\chi_{d}^{2}$ with $d=n-1$. If we set

$$
(n-1) \frac{S^{2}}{\sigma_{X}^{2}}=W_{d}^{2}, d=n-1
$$

then denoting by $\left(W_{d}^{2}\right)_{A}$ the value of $W_{d}^{2}$ for which

$$
P\left(W_{d}^{2} \leq\left(W_{d}^{2}\right)_{A}\right)=A
$$

we have

$$
A=\int_{0}^{\left(W_{d}^{2}\right)_{A}} \chi_{d}^{2}(x) d x
$$

is the area under the graph of $\chi_{d}^{2}$ to the left of $\left(W_{d}^{2}\right)_{A}$.
So we want a region of area $C$ in the middle under the graph of $\chi_{d}^{2}$ and that means we symmetrically want the range of values of $W_{d}^{2}$ from $\left(W_{d}^{2}\right)_{A}$, to $\left(W_{d}^{2}\right)_{B}$, where $A=(1-C) / 2$, and $B=1-(1-C) / 2=(1+C) / 2$.

Therefore,

$$
P\left[\left(W_{d}^{2}\right)_{A} \leq \frac{(n-1) S^{2}}{\sigma_{X}^{2}} \leq\left(W_{d}^{2}\right)_{B}\right]=C
$$

Since taking reciprocals reverses the order for positive numbers, the inequality in the brackets is equivalent to

$$
\frac{(n-1) S^{2}}{\left(W_{d}^{2}\right)_{B}} \leq \sigma_{X}^{2} \leq \frac{(n-1) S^{2}}{\left(W_{d}^{2}\right)_{A}}
$$

so this is the confidence interval for $\sigma_{X}^{2}$ with confidence level $C$.

## 32. SAMPLING TWO INDEPENDENT UNKNOWNS

When trying to determine the difference in means of two exclusive populations, we can form the population of all pairs which can be formed by taking the first member of the pair from the first population and the second member of the pair from the second population. Specifically, if $A$ and $B$ are sets and $X$ is a random variable on $A$ and $B$ is a random variable on $B$, then we can form the Cartesian Product, denoted $A \times B$, and defined by

$$
A \times B=\{(a, b): a \in A \& b \in B\}
$$

A random variable $X$ on $A$ is a real-valued function which when the outcome is $a \in A$ the value of $X$ is the number $X(a)$. Likewise, if $Y$ is a random variable on $B$, then for $b \in B$, the value $Y(b)$ is the value of $Y$ for the outcome $b$. The random variable $X$ can then be viewed as a random variable on the set $A \times B$ by defining

$$
X(a, b)=X(a)
$$

and likewise, $Y$ can be viewed as a random variable on $A \times B$ by defining

$$
Y(a, b)=Y(b)
$$

Thus, on $A \times B$, the variable $X$ ignores the second entry of a pair and $Y$ ignores the first entry of a pair. The result is that $X$ and $Y$ become independent random variables on the common population $A \times B$.

Suppose now we have $X_{1}, X_{2}, X_{3}, \ldots, X_{n_{X}}$ and $Y_{1}, Y_{2}, Y-3, \ldots, Y_{n_{Y}}$ are independent random samples for each random variable, so $\bar{X}_{n_{X}}$ or simply $\bar{X}$ is the sample mean random variable for the population $A$, and likewise $\bar{Y}_{n_{Y}}$ or simply $\bar{Y}$ is the sample mean random variable for the population $B$. These two sample mean random variables then become independent random variables on $A \times B$, and

$$
E(\bar{X}-\bar{Y})=\mu_{X}-\mu_{Y}
$$

But, since they are indepedent,

$$
S D(\bar{X}-\bar{Y})=\sqrt{\operatorname{Var}(\bar{X})+\operatorname{Var}(\bar{Y})}
$$

On the other hand, since the samples are IRS's,

$$
\operatorname{Var}(\bar{X})=\frac{\sigma_{X}^{2}}{n_{x}} \text { and } \operatorname{Var}(\bar{Y})=\frac{\sigma_{Y}^{2}}{n_{Y}}
$$

Therefore

$$
S D(\bar{X}-\bar{Y})=\sqrt{\frac{\sigma_{X}^{2}}{n_{X}}+\frac{\sigma_{Y}^{2}}{n_{Y}}}
$$

Thus, if $\sigma_{X}$ and $\sigma_{Y}$ are known, then for the case of normal random variables, the margin of error with confidence $C$ in a confidence level is simply

$$
z_{C} \cdot S D(\bar{X}-\bar{Y})
$$

where

$$
z_{C}=\operatorname{invNorm}\left(\frac{1+C}{2}, 0,1\right)
$$

If you do not know $\sigma_{X}^{2}$ and $\sigma_{Y}^{2}$, then you must estimate them from the sample data using sample variances $S_{X}^{2}$ and $S_{Y}^{2}$. Of course then, you are dealing with the distribution of

$$
t_{d}=\frac{\bar{X}-\bar{Y}-\left(\mu_{X}-\mu_{Y}\right)}{\sqrt{\frac{S_{X}^{2}}{n_{X}}+\frac{S_{Y}^{2}}{n_{Y}}}}
$$

and in certain cases, this can be shown to be a $t$-distribution for $d$ degrees of freedom. How to find $d$ then is the next problem, and the result depends on the type of situation.

CASE $\sigma_{X}=\sigma_{Y}$.
Then with $\sigma_{X}=\sigma=\sigma_{Y}$, we have

$$
S D(\bar{X}-\bar{Y})=\sqrt{\sigma^{2}\left(\frac{1}{n_{X}}+\frac{1}{n_{Y}}\right)}
$$

In this case, $\left(n_{X}-1\right) S_{X}^{2} / \sigma^{2}$ and $\left(n_{Y}-1\right) S_{Y}^{2} / \sigma^{2}$, are independent chi-square distributed variables with degrees of freedom $d f_{X}=n_{X}-1$ and $d f_{Y}=n_{Y}-1$, respectively, so their sum,

$$
\frac{\left(n_{X}-1\right) S_{X}^{2}}{\sigma^{2}}+\frac{\left(n_{Y}-1\right) S_{Y}^{2}}{\sigma^{2}}=\frac{\left(n_{X}-1\right) S_{X}^{2}+\left(n_{Y}-1\right) S_{Y}^{2}}{\sigma^{2}}
$$

also has chi-square distribution with degrees of freedom the total for each sample. Here $S_{\text {pool }}^{2}$, called the Pooled Variance defined by

$$
S_{\text {pool }}^{2}=\frac{d f_{X} \cdot S_{X}^{2}+d f_{Y} \cdot S_{Y}^{2}}{d f_{X}+d f_{Y}}
$$

then has the property

$$
\frac{S_{p o o l}^{2}}{\sigma^{2}}=\frac{W_{d}^{2}}{d}, d=d f_{X}+d f_{Y}
$$

with $W_{d}^{2}$ having the chi-square distribution for $d$ degrees of freedom found by simply adding degrees of freedom for each sample,

$$
d=d f_{X}+d f_{Y}
$$

Case where standard deviations are unknown and there relationship to each other is unkown.

Here, the distribution is not really known, but there seems to be consensus among statisticians that

$$
\frac{W_{d}^{2}}{d}=\frac{\frac{S_{X}^{2}}{n_{X}}+\frac{S_{Y}^{2}}{n_{Y}}}{S D(\bar{X}-\bar{Y})}
$$

where $W_{d}$ should be chi-square distributed for some number of degrees of freedom $d$, and the two terms in the numerator on the right hand side are independent of each other. The expected value of any chi-square distribution is the number of degrees of freedom, but our equation does not give us anything other than $d / d=1$, a triviality. Using independence of the two terms in the numerator allows us to compute the variance of the numerator and equate that to the variance of $W_{d}^{2}$ to get an equation for $d$. The result is (for instance, see EXPECTATION PRIMER)

$$
d=\frac{\left(\frac{\sigma_{X}^{2}}{n_{X}}+\frac{\sigma_{Y}^{2}}{n_{Y}}\right)^{2}}{\frac{1}{d f_{X}}\left(\frac{\sigma_{X}^{2}}{n_{X}}\right)^{2}+\frac{1}{d f_{Y}}\left(\frac{\sigma_{Y}^{2}}{n_{Y}}\right)^{2}}
$$

Notice now that $d$ may not even be a whole number and that we need the values of the standard deviations to know the degrees of freedom. Accepted practice here is to use the sample standard deviations in place of the actual standard deviations to determine the degrees of freedom $d$, and then the confidence interval is calculated with the $t$-distribution for $d$ degrees of freedom.

